

Master's Thesis Defense

01

MetaRec Meta-Learning Meets Recommendation Systems

Presented by **James Le**

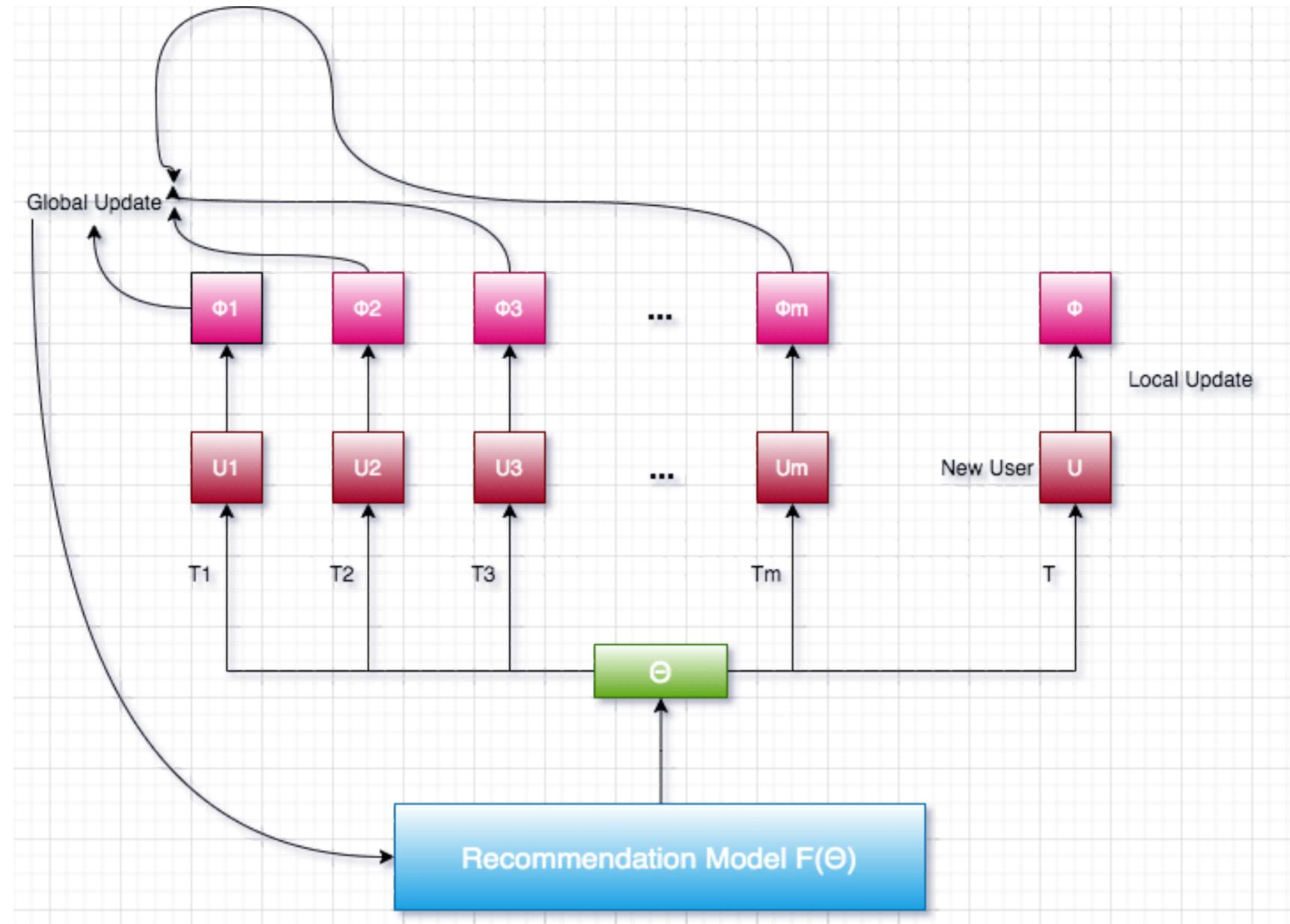
Advised by **Alexander Ororbia II**

As Member of **Neural Adaptive Computing Lab**



Outline

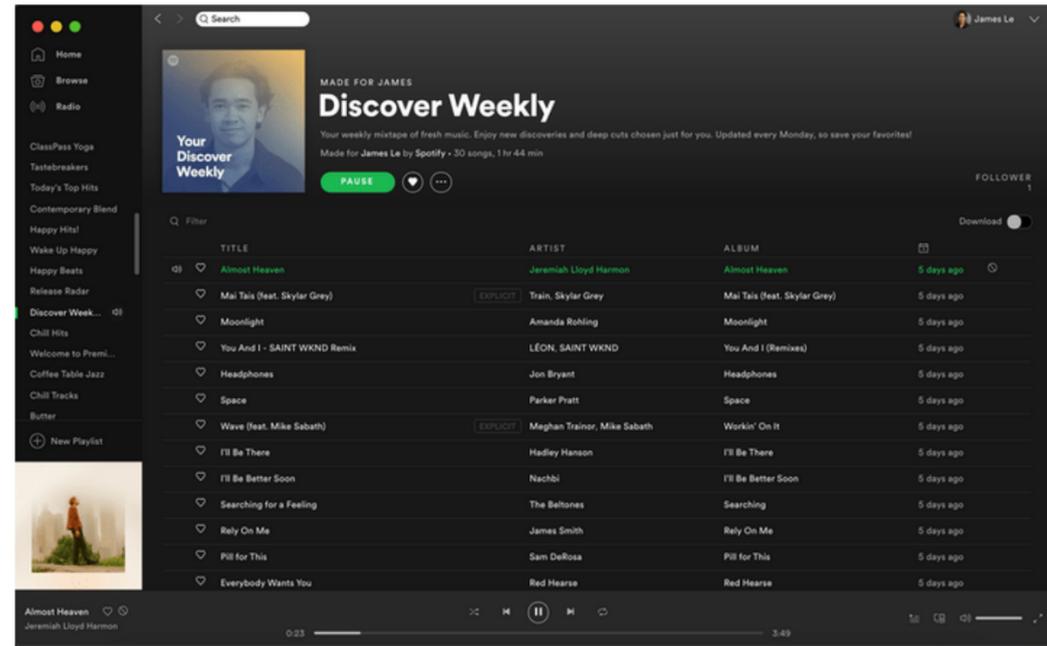
- 1 - Introduction
- 2 - Recommendation Systems
- 3 - Meta Learning
- 4 - MetaRec
- 5 - Experiments
- 6 - Conclusion



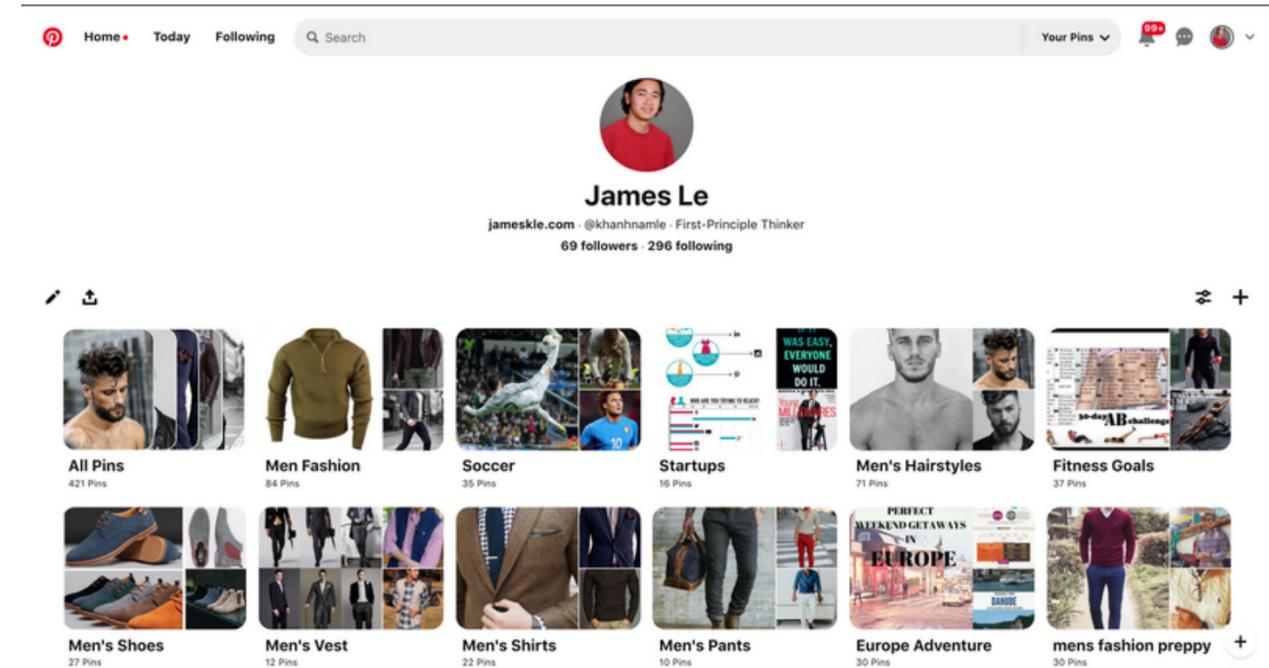
Introduction

PART 1

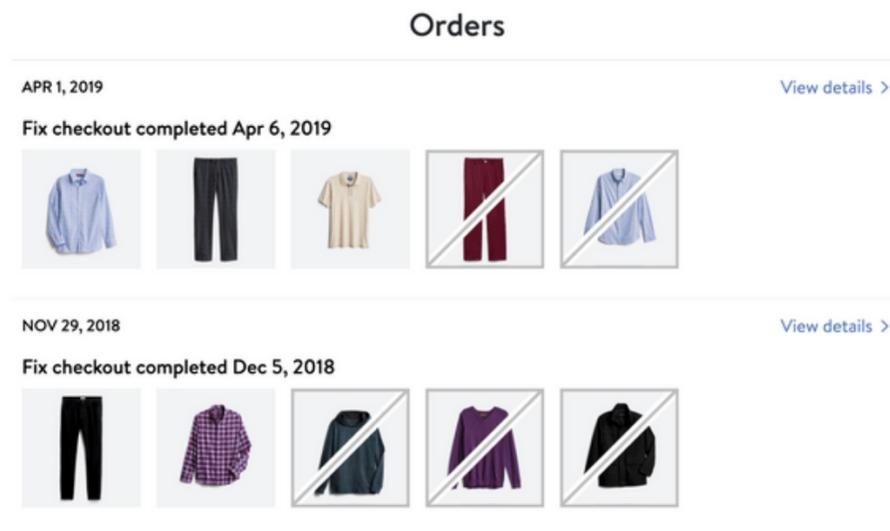
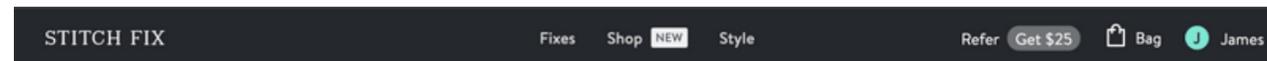




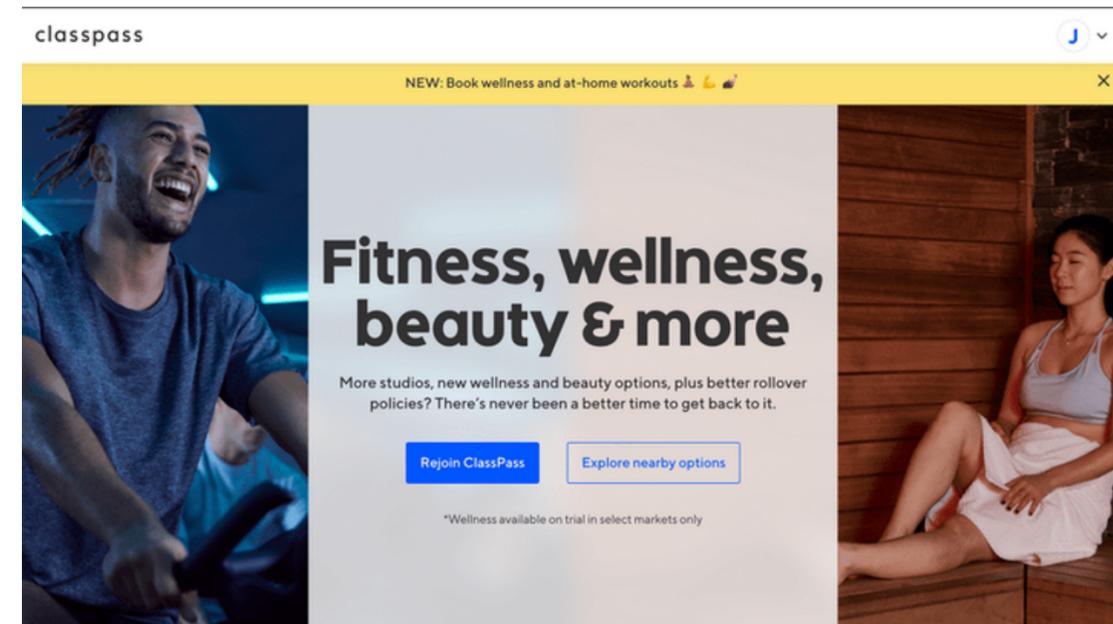
ENTERTAINMENT



CONTENT



E-COMMERCE



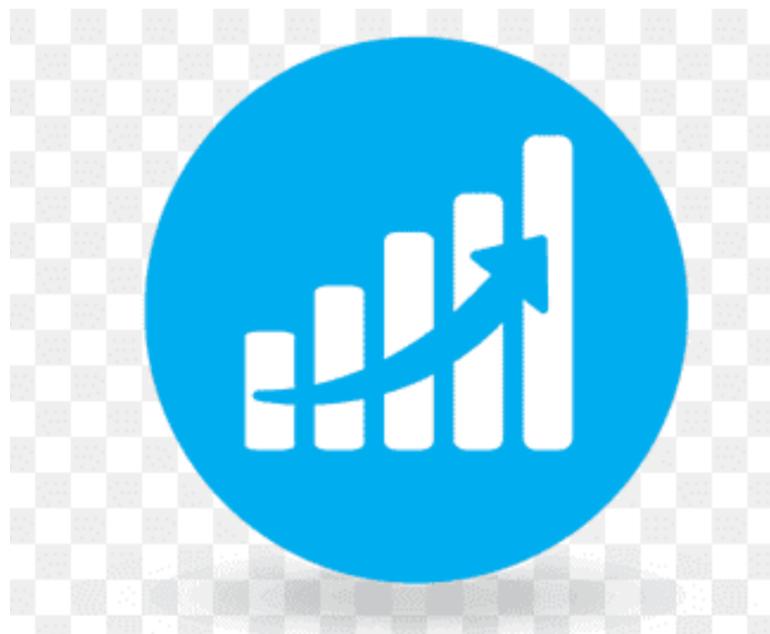
SERVICES

Challenges

WHAT I WANT TO TACKLE



Scalability

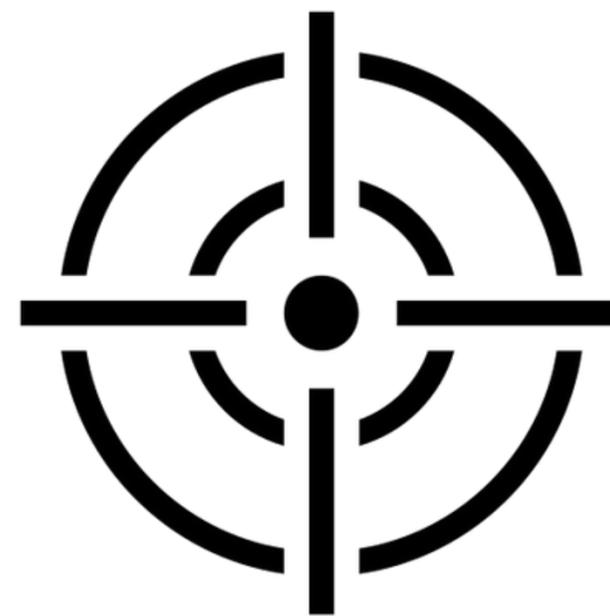


Sparsity

A					
B					
C					
D					
E					



Accuracy



Challenges

WHAT I WANT TO TACKLE



Scalability

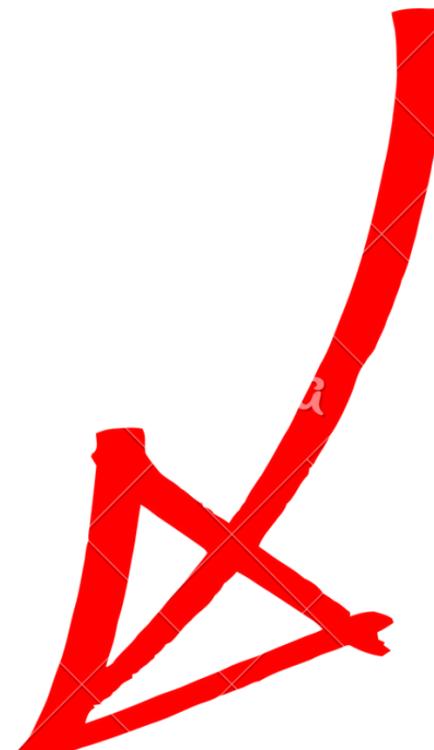


Sparsity

A					
B					
C					
D					
E					



Accuracy



"RECOMMENDATION SYSTEMS THAT META-LEARN
INFORMATION FROM RELATED TASKS
OUTPERFORM SYSTEMS THAT DO NOT USE THIS
INFORMATION ACROSS A WIDE RANGE OF TASKS
IN ACCURACY METRICS."

Recommendation Systems

PART 2

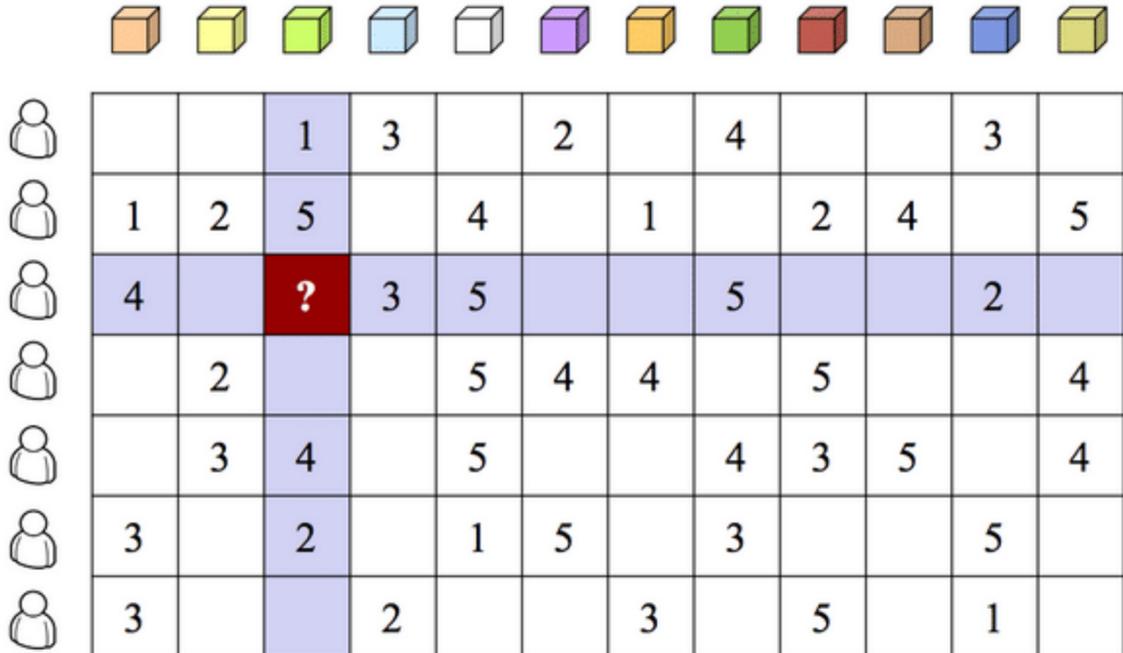


Problem Formulation

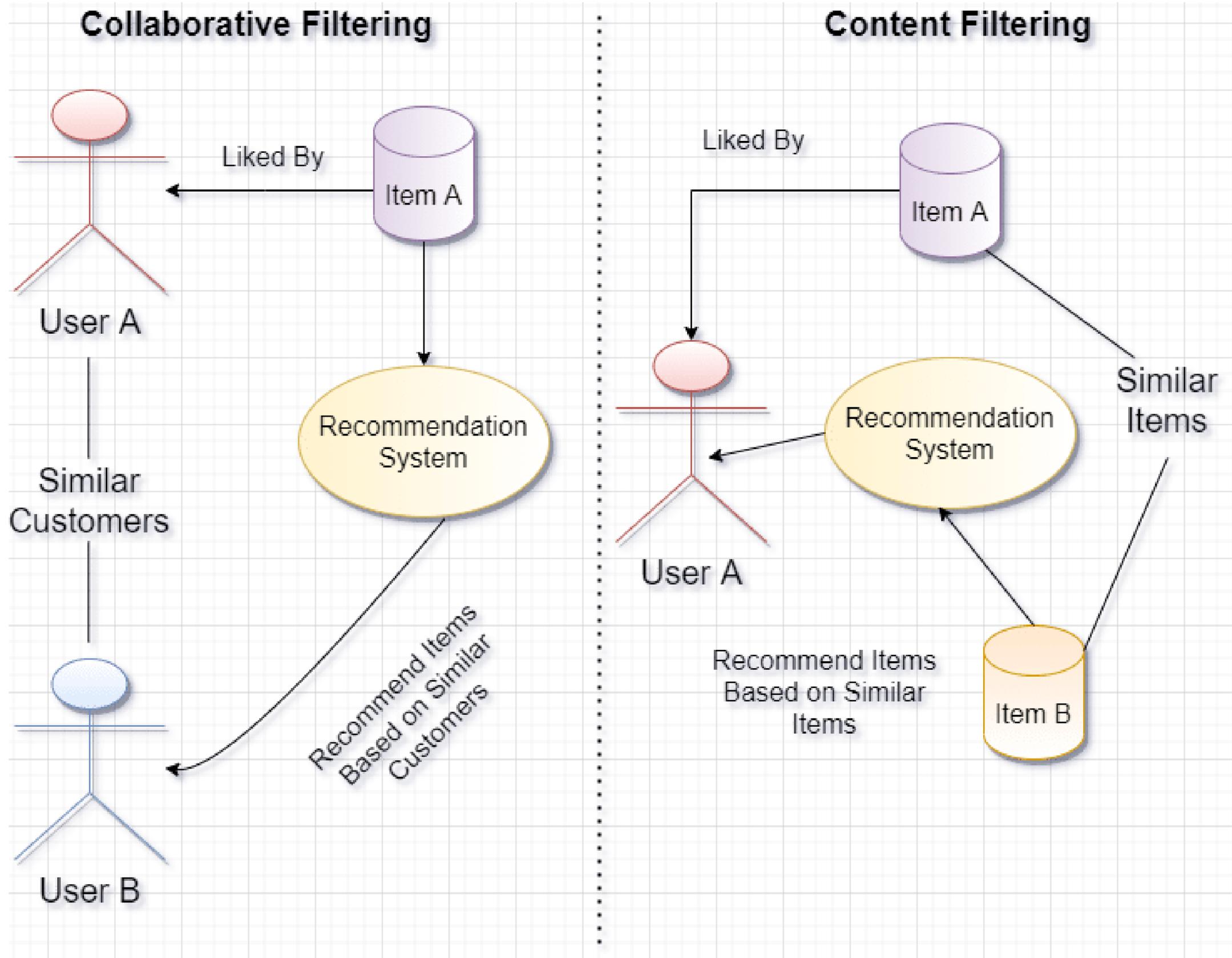
- U - set of all users
- I - set of all items
- $F(u, i)$ - utility function that measures the relevance of item i to user u
- F is usually represented as a rating in numeric scale

$$\forall u \in U, i_s = \arg \max_{i \in I} F(u, i)$$

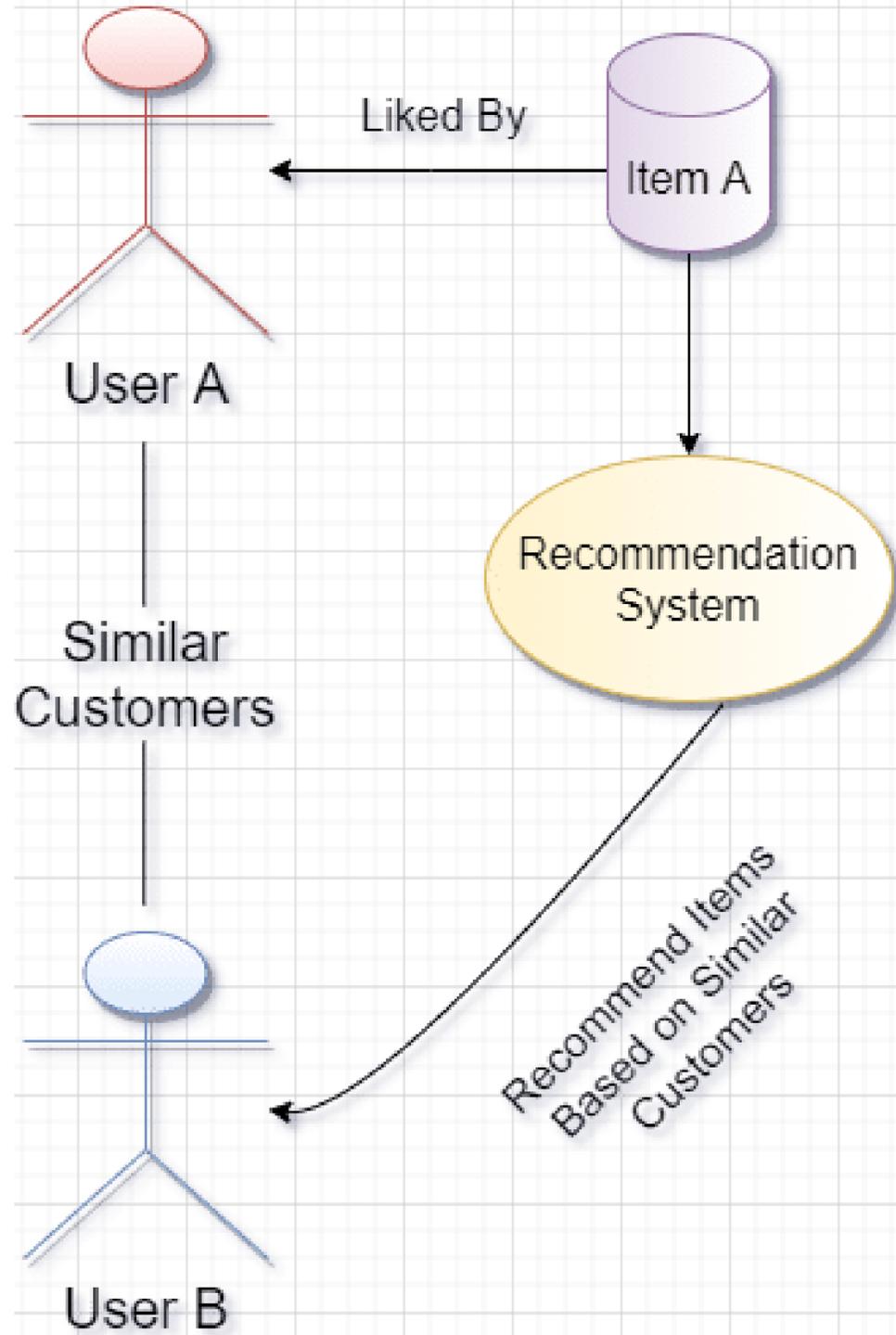
Items \mathcal{I}



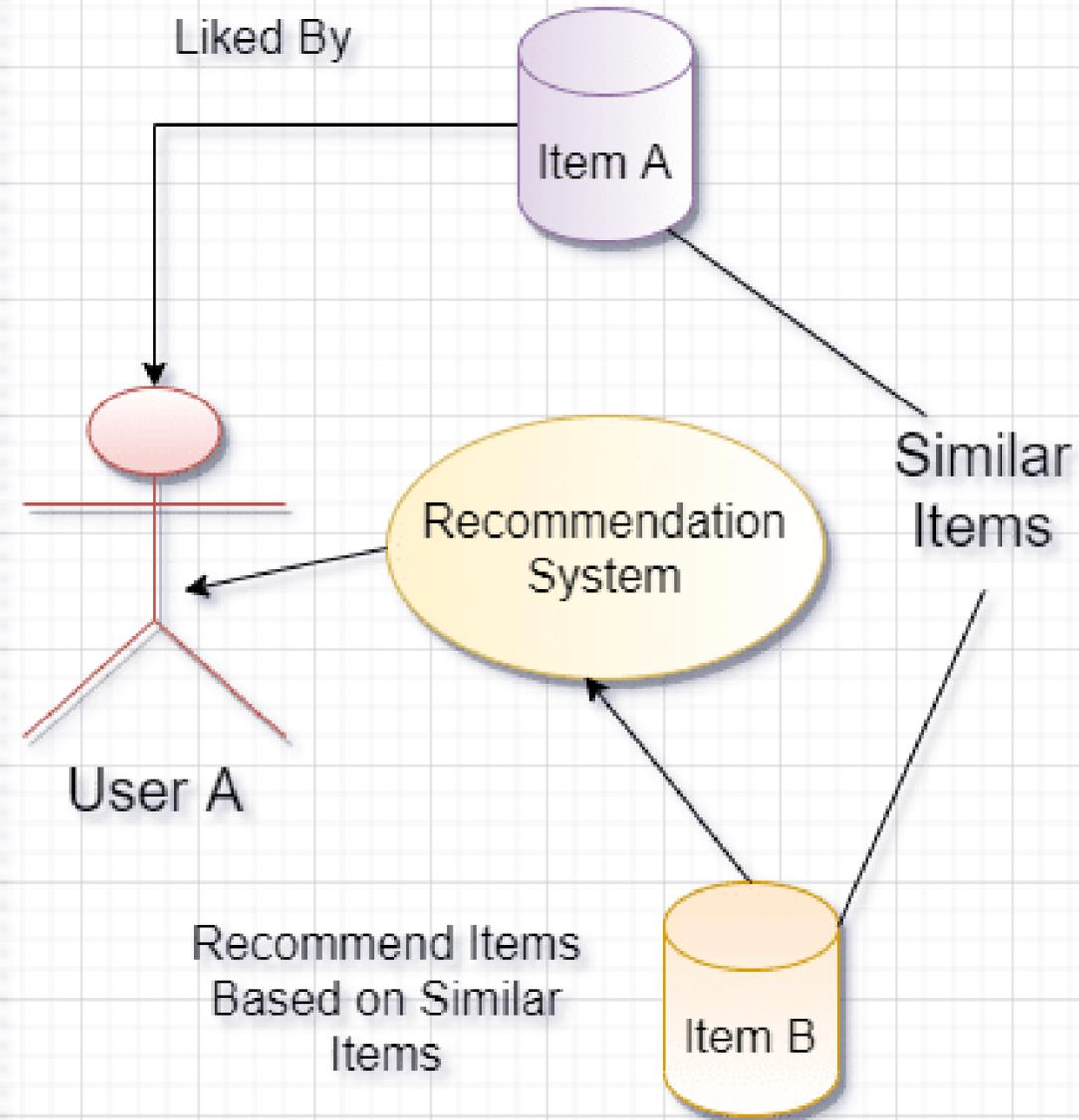
		1	3		2		4			3		
1	2	5		4		1		2	4		5	
4		?	3	5			5			2		
	2			5	4	4		5				4
	3	4		5			4	3	5			4
3		2		1	5		3			5		
3			2			3		5		1		



Collaborative Filtering

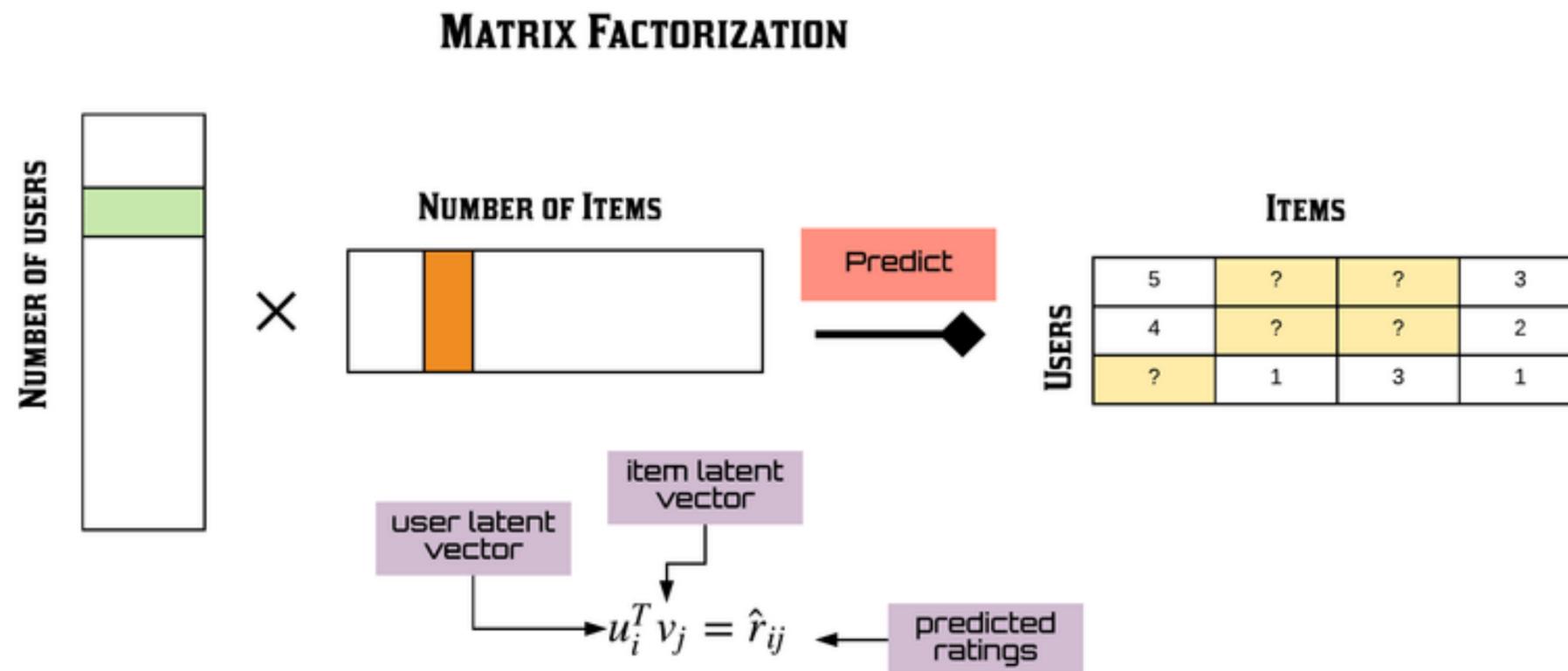


Content Filtering

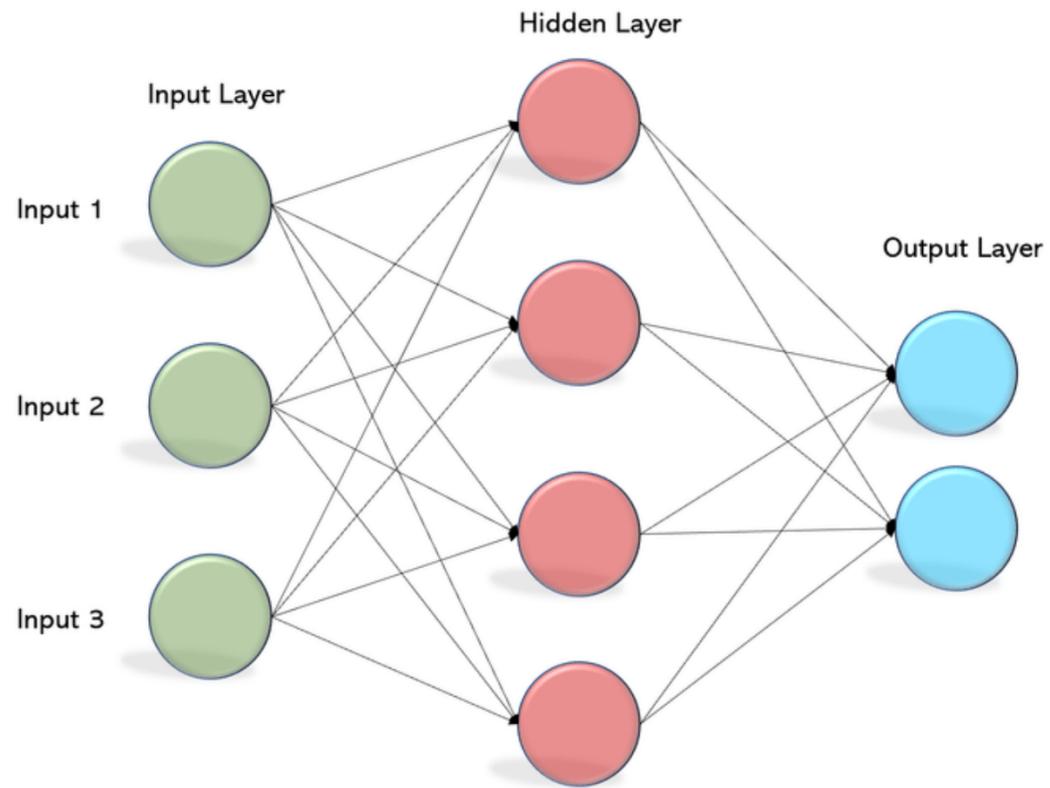


Matrix Factorization

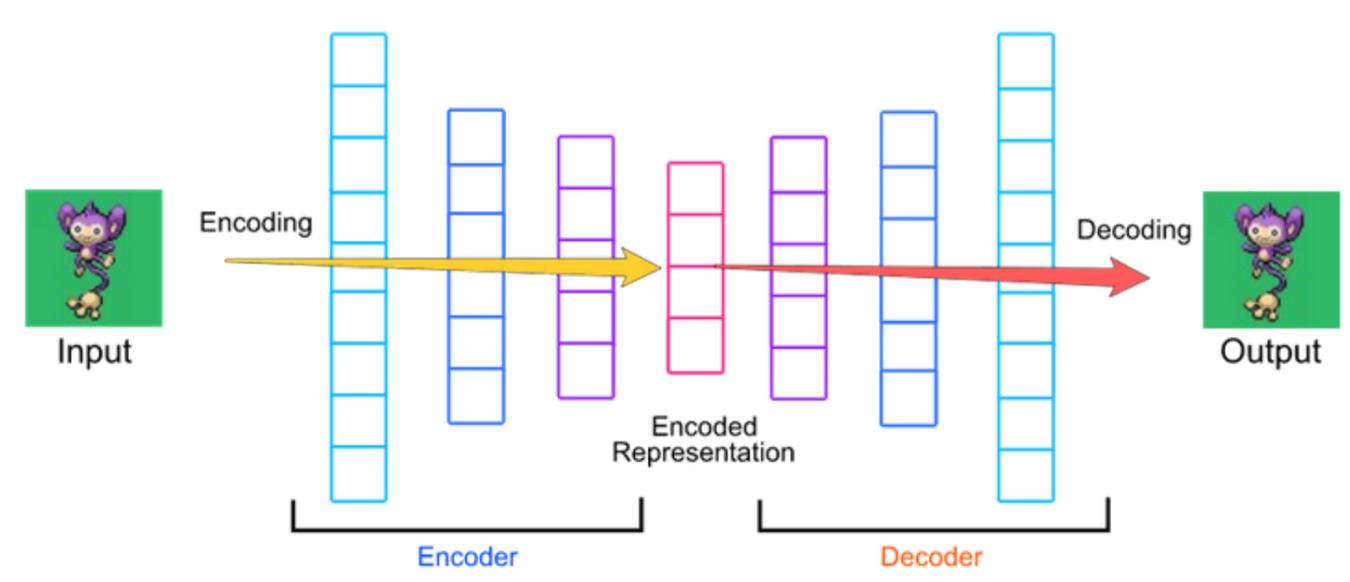
- The de-facto standard for collaborative filtering
- Represent user preferences as an user-item matrix
- Find two smaller matrices (latent embeddings) that approximate the full matrix
- Minimize the rating prediction errors
- Can be optimized via Gradient Descent
- Prediction is simple



Neural Networks



MULTI-LAYER PERCEPTRON



AUTOENCODER



Neural Networks For Recommendations

SOLUTIONS FOR EXISTING CHALLENGES

SCALABILITY

- Extract low-dimensional factors of high-dimensional user preferences for the items

SPARSITY

- Engineer content-based features and integrate them into the algorithm
- Extract high-level representations of user preferences for the items

ACCURACY

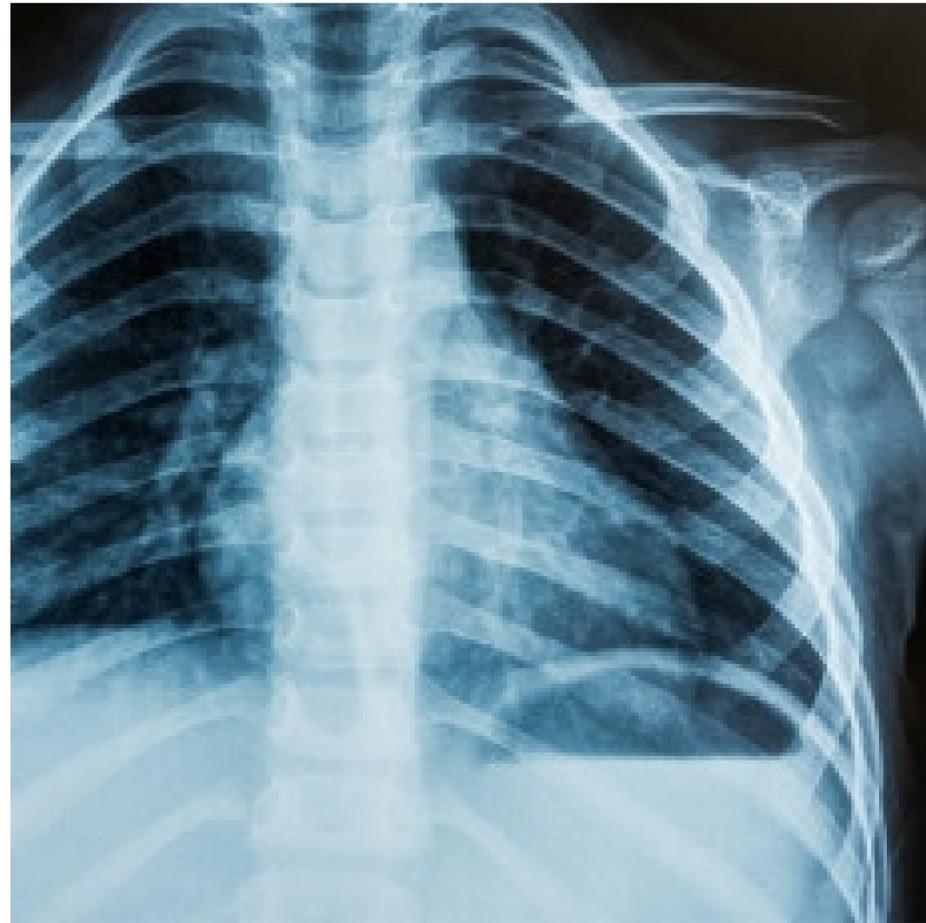
- Extract user and item's latent factors
- Jointly combine information from different data sources and modalities

Meta Learning

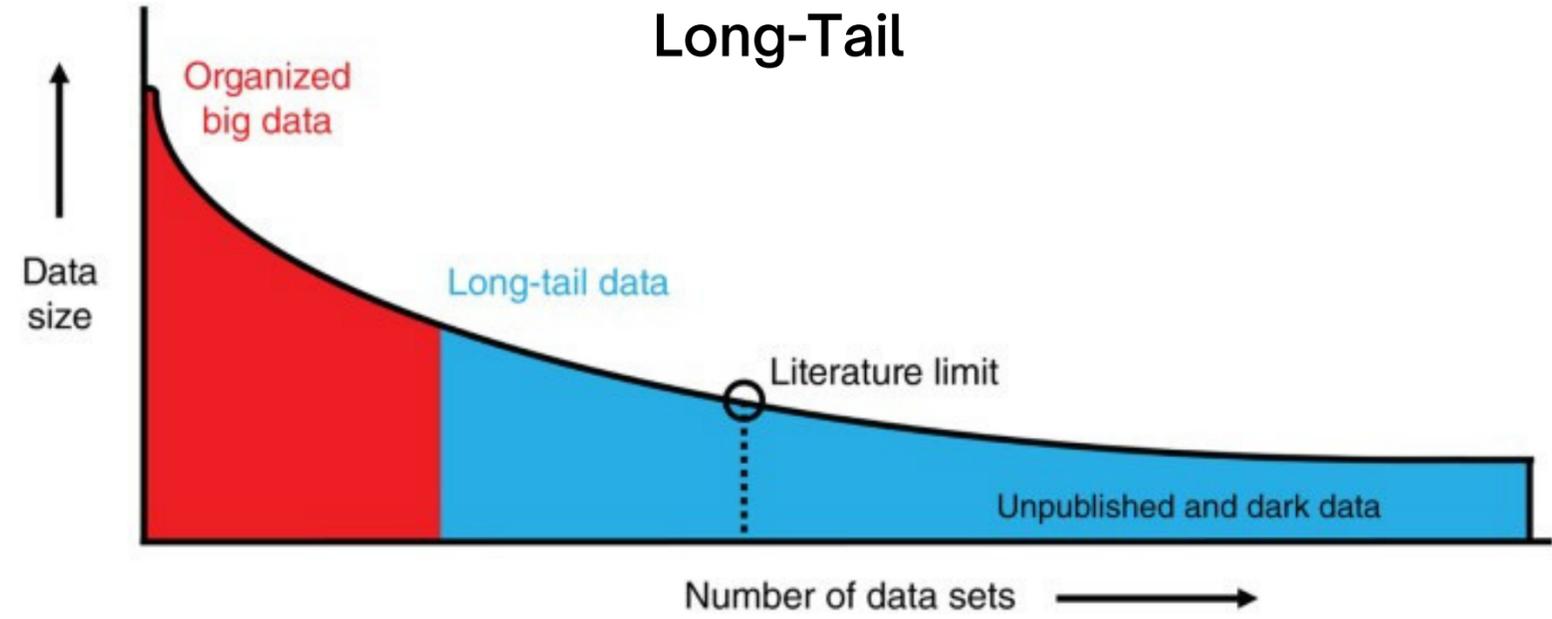
PART 3



Motivation



Limited Data



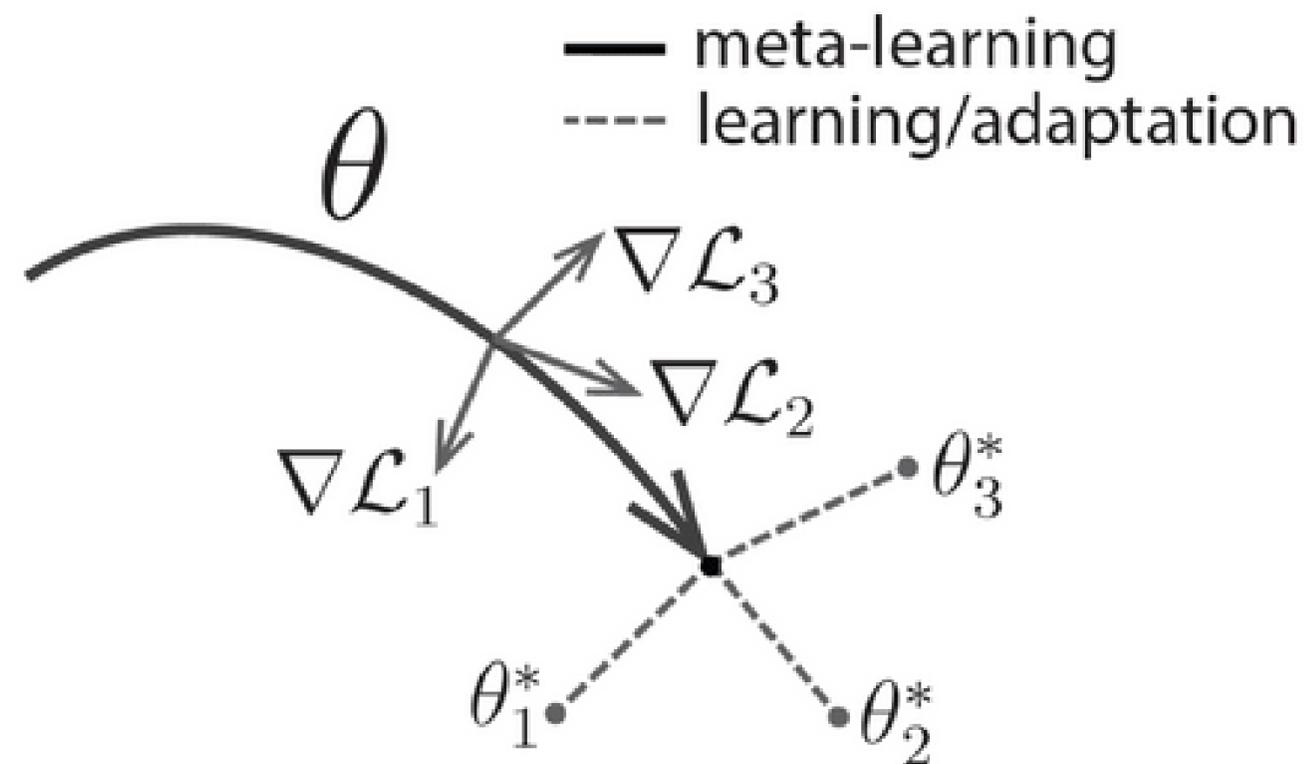
Fast Inference

Model-Agnostic Meta-Learning (MAML, Finn et. al, 2017)

$$\min_{\theta} \sum_{\text{tasks } i} \mathcal{L}_{\text{val}}^{(i)}(\theta - \alpha \nabla_{\theta} \mathcal{L}_{\text{train}}^{(i)}(\theta))$$

θ parameter vector
being meta-learned

θ_i^* optimal parameter
vector for task i



MetaRec

PART 4



Binary Classification: $P(r_{ui} = 1|p_u, q_i) = F_{\theta}(p_u, q_i, \theta)$

Rating Regression: $\hat{r}_{ui} = F_{\theta}(p_u, q_i, \theta)$

$$\phi_u = \theta - \alpha \nabla_{\theta} L_{T_u}(F_{\theta})$$

$$\theta = \theta - \beta \nabla_{\theta} \sum_{T_u \sim B} L_{T_u}(F_{\phi_u})$$

RECOMMENDATION TASK

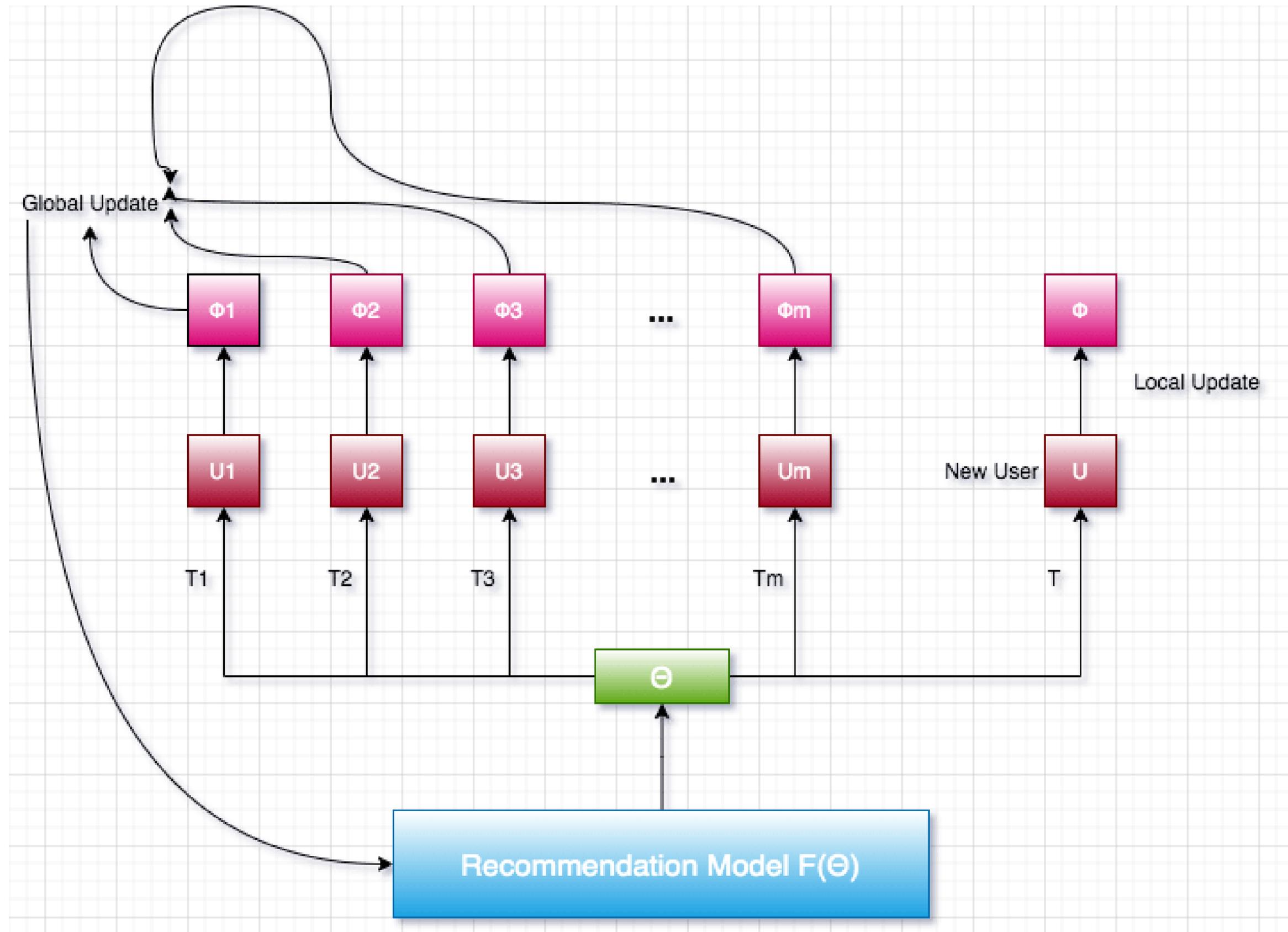
- Task T = Recommend items to one user given examples of items already rated by that user
- Binary Classification (Implicit Feedback)
- Rating Regression (Explicit Feedback)
- θ denotes model parameters

LOCAL UPDATE

- Sample a batch of tasks B
- Uses MAML to compute task-specific parameters ϕ based on the loss function value for each task T in batch B
- α is the local learning rate

GLOBAL UPDATE

- Uses MAML to compute model parameters θ on the sum of test losses for all tasks T
- β is the global learning rate



Experiments

PART 5



Matrix Factorization Experiments

BASELINE MODELS

Vanilla Matrix Factorization
(Koren et al., 2009)

$$r_{ui} = p_u \cdot q_i^T$$

Matrix Factorization with Biases
(Koren et al., 2009)

$$r_{ui} = b + \omega_u + \omega_i + p_u \cdot q_i^T$$

Matrix Factorization with Side Features
(Koren et al., 2009)

$$r_{ui} = b + d_o + \omega_u + \omega_i + (p_u + t_o) \cdot q_i^T$$

Matrix Factorization with Temporal Features
(Koren et al., 2009)

$$r_{ui} = b + \omega_u + \omega_i + p_u \cdot q_i^T + m_u \cdot n_t$$

Matrix Factorization Experiments

BASELINE MODELS

Factorization Machine
(Rendle, 2010)

$$r_{ui} = b + \sum_{i=1}^n \omega_i \cdot x_i + \sum_{i=1}^n \sum_{j=i+1}^n \langle v_i, v_j \rangle x_i \cdot x_j \quad \mathbf{w} \in \mathbb{R}^n, \quad \mathbf{V} \in \mathbb{R}^{n \times k}$$

Matrix Factorization with Mixture of Taste
(Kula, 2018)

$$r_{ui} = \sigma(A_u \cdot q_i^T) \cdot (U_u \cdot q_i^T) + b + \omega_u + \omega_i$$

$$\sigma(x_i) = \frac{\exp^{x_i}}{\sum_j \exp^{x_j}} \quad A \in \mathbb{R}^{m \times k}, U \in \mathbb{R}^{m \times k}$$

Variational Matrix Factorization
(Porteus et al., 2010, Kim et al., 2014)

$$r_{ui} = b + \omega_u + \omega_i + GS(\mu_u, v_u) \cdot GS(\mu_i, v_i)$$

$$GS(\mu, v) = \mu + \mathcal{N}(0, 1) \cdot \sqrt{v}$$

MetaRec-MF

BASE MODEL

Matrix Factorization with Biases

$$\hat{r}_{ui} = F(u, i | p_u, q_i, \theta) = p_u \cdot q_i + b + w_u + w_i$$

LOSS FUNCTION

Mean-Squared Error with L2 Regularization

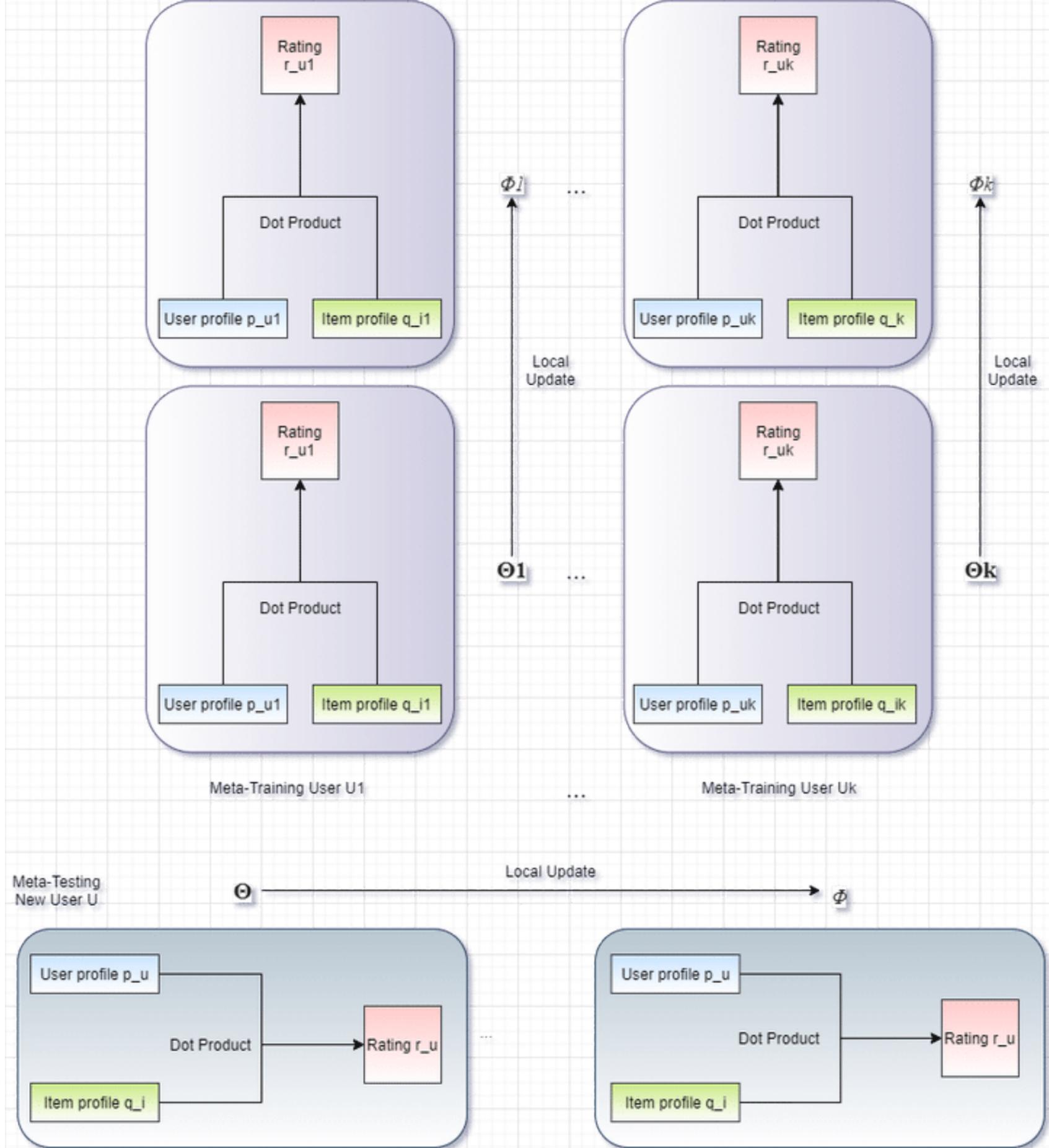
$$L(\theta) = \frac{1}{|D_{train}|} \sum_{r_{u,i} \in D_{train}} (r_{u,i} - \hat{r}_{u,i})^2 + \lambda \frac{1}{2} \|\theta\|_2^2$$

EVALUATION METRICS

- Rating Regression with Explicit Feedback
- Mean Squared Error
- Mean Absolute Error

$$MAE = \frac{1}{|D_{test}|} \sum_{r_{u,i} \in D_{test}} |r_{u,i} - \hat{r}_{u,i}|$$

$$MSE = \frac{1}{2|D_{test}|} \sum_{r_{u,i} \in D_{test}} (r_{u,i} - \hat{r}_{u,i})^2$$



Regression Results

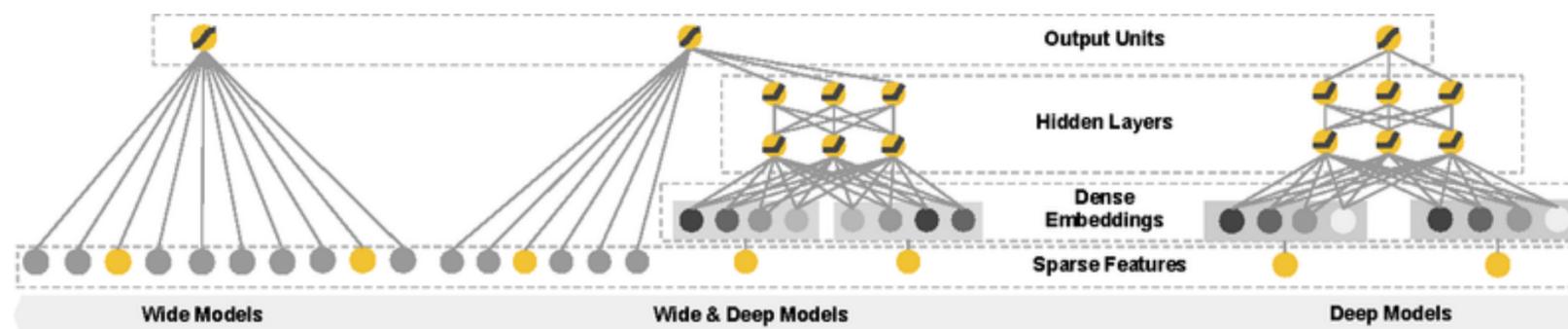
Models	MAE	MSE	Training Time
MF	0.703	0.817	6m5s
MF-Bias	0.694	0.790	11m38s
MF-Side	0.691	0.784	13m34s
MF-Temporal	0.689	0.793	18m51s
FM	0.712	0.823	3m40s
MF-Mixture	0.687	0.788	13m44s
Variational-MF	0.707	0.839	16m51s
MetaRec-MF (Ours)	0.687	0.760	12m45s

- Train-Test Split: 75-25
- Trained for 50 Epochs
- MetaRec-MF outperforms the other models on both MAE and MSE metrics (Lower values are better)
- Slight tradeoff between accuracy performance and compute cost
- The Factorization Machine model took the fastest time to train
- Adding more features to the matrix factorization equation led to longer training time

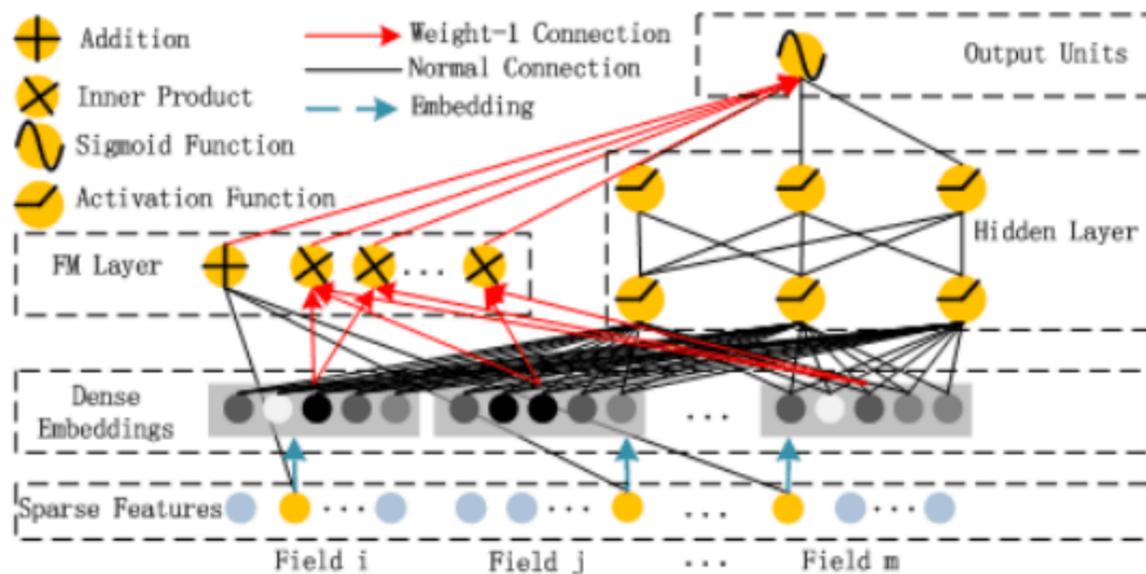
Multi-Layer Perceptron Experiments

BASELINE MODELS

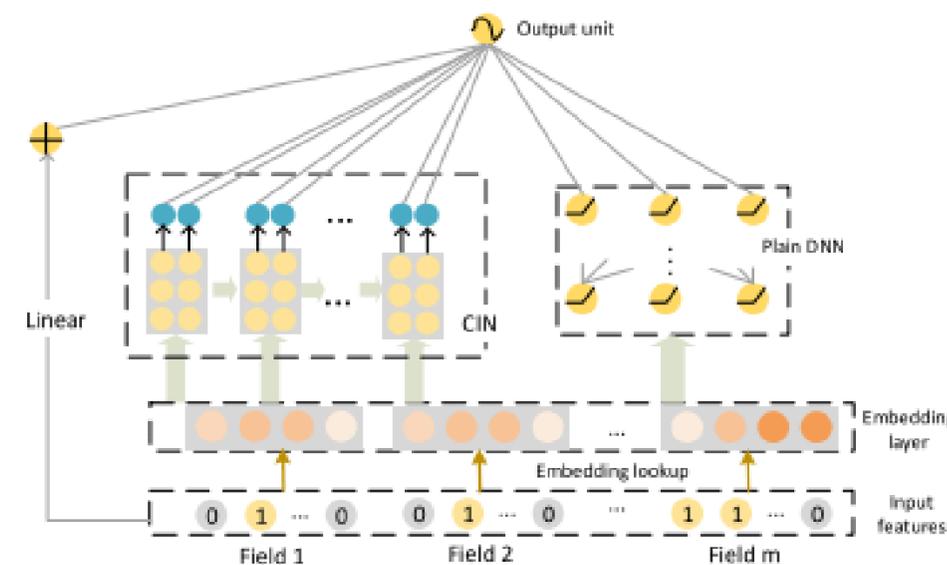
Wide and Deep (Cheng et al., 2016)



Deep Factorization Machine (Guo et al., 2017)



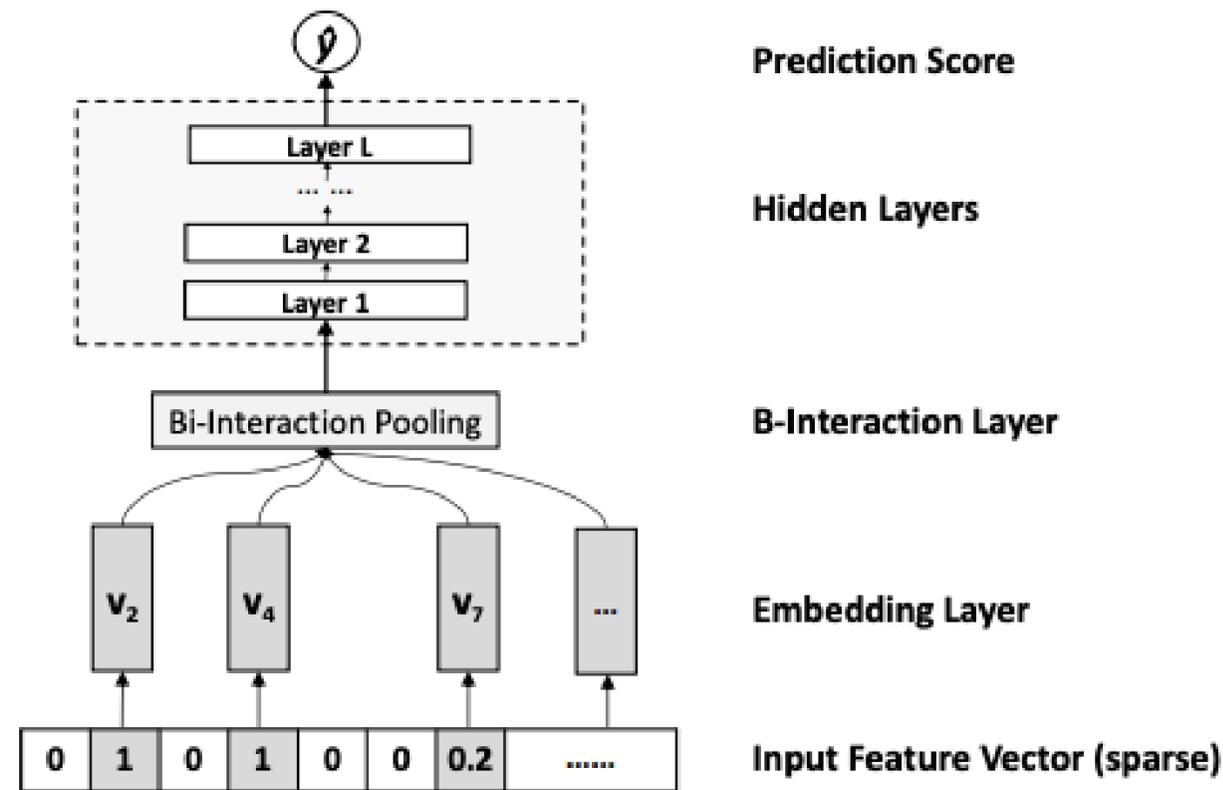
Extreme Deep Factorization Machine (Lian et al., 2018)



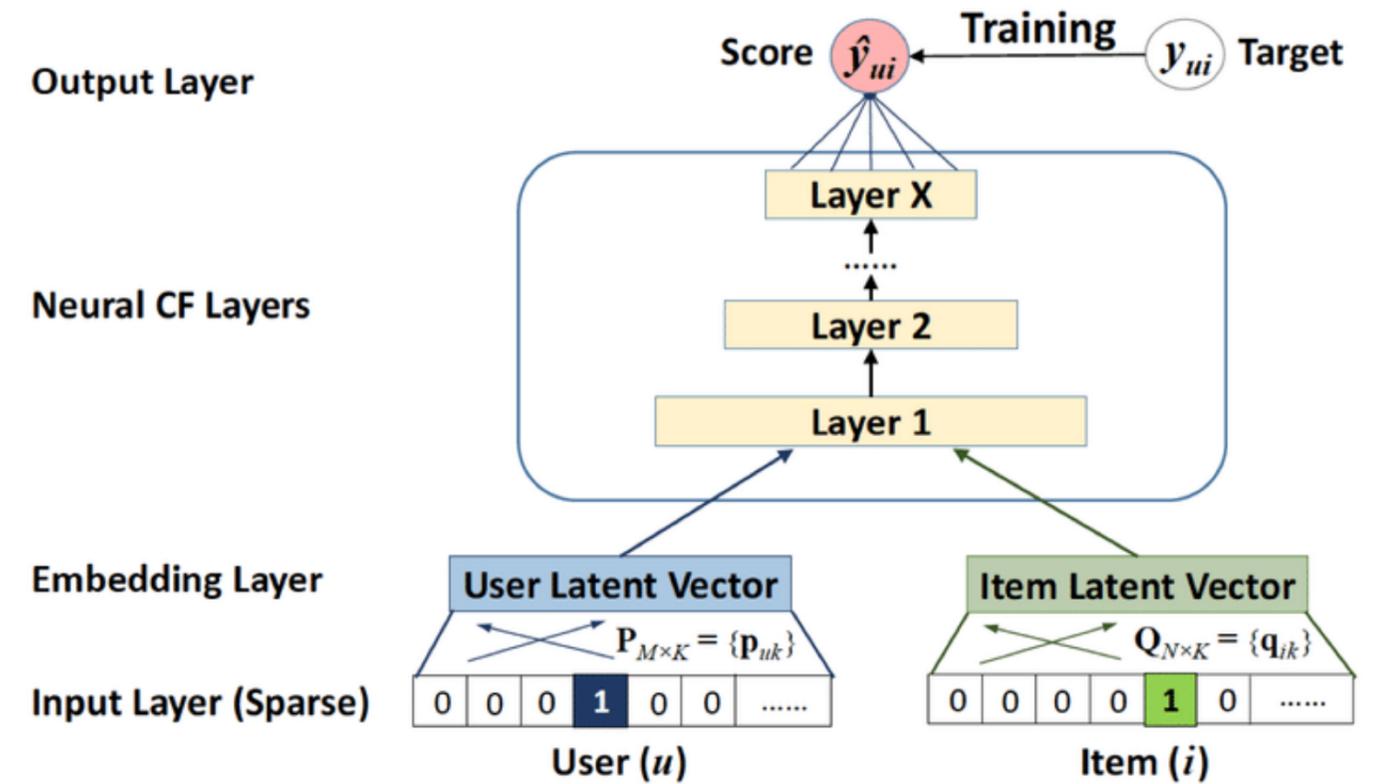
Multi-Layer Perceptron Experiments

BASELINE MODELS

Neural Factorization Machines (He et al., 2017)



Neural Collaborative Filtering (He et al., 2017)



MetaRec-MLP

BASE MODEL

Neural Collaborative Filtering

$$e_u = F_{\theta_u}(p_u)$$

$$e_i = F_{\theta_i}(q_i)$$

$$x_0 = [e_u, e_i],$$

$$x_1 = \sigma(W_1 x_0 + b_1),$$

...

$$x_m = \sigma(W_m x_{m-1} + b_m),$$

$$\hat{r}_{ui} = \sigma(W_o x_m + b_o)$$

LOSS FUNCTION

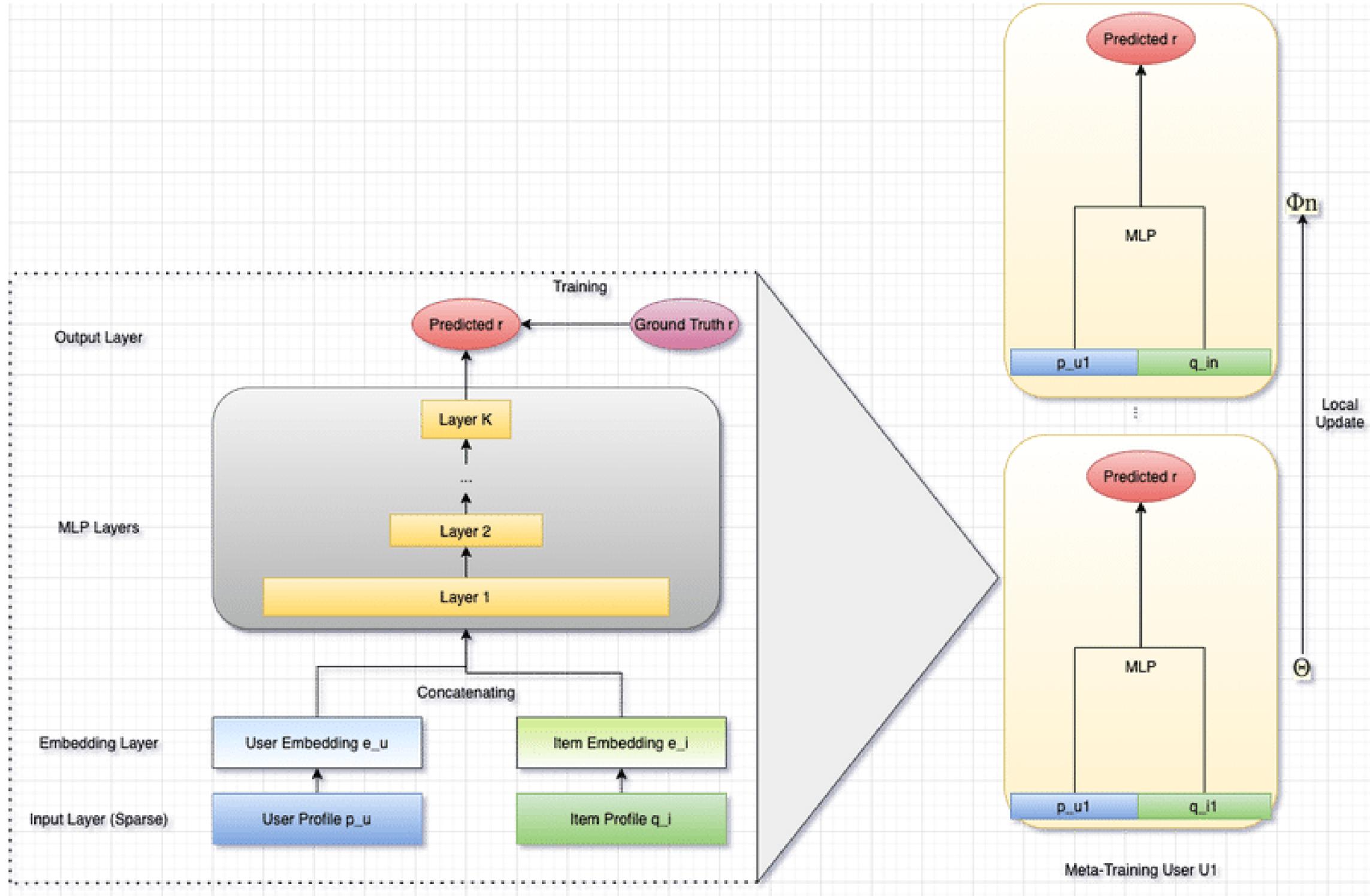
Binary Cross-Entropy Loss

$$L_u(F_{\theta, \phi_u}) = -\frac{1}{|B|} \sum_{i \in B} (r_{ui} \log \hat{r}_{ui}) + (1 - r_{ui}) \log(1 - \hat{r}_{ui})$$

EVALUATION METRICS

- Binary Classification with Implicit Feedback
- Area Under the ROC Curve (AUC)

ADAPTED FROM (HE ET AL., 2017)



Classification Results

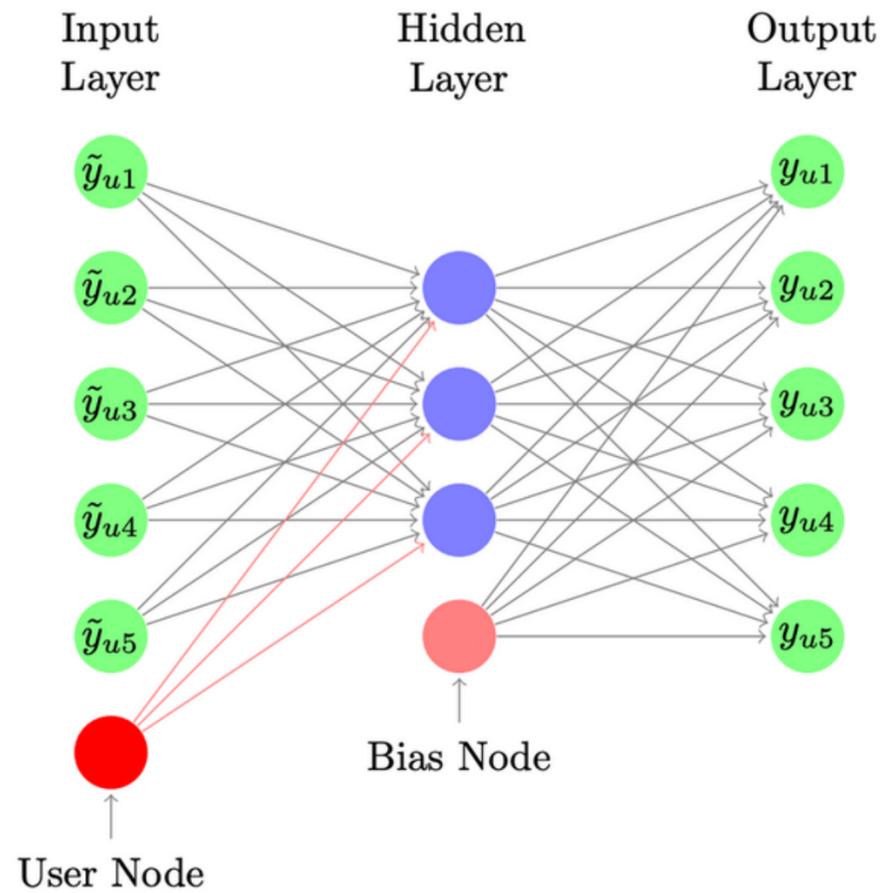
Models	Test AUC	Validation AUC	Training Time
WideDeep	0.7991	0.7995	1h12m15s
DeepFM	0.7915	0.7918	1h10m50s
xDeepFM	0.7429	0.7408	2h15m17s
NeuralFM	0.7589	0.7560	1h36m0s
NeuralCF	0.7668	0.7673	54m15s
MetaRec-MLP (Ours)	0.8135	0.8127	1h05m3s

- Train-Valid-Test Split: 80-10-10
- Trained for 100 Epochs
- MetaRec-MLP outperforms other methods in AUC performance on both test and validation sets (Higher values are better)
- Tradeoff between model performance and compute cost
- WideDeep and DeepFM perform reasonably well
- xDeepFM overfits

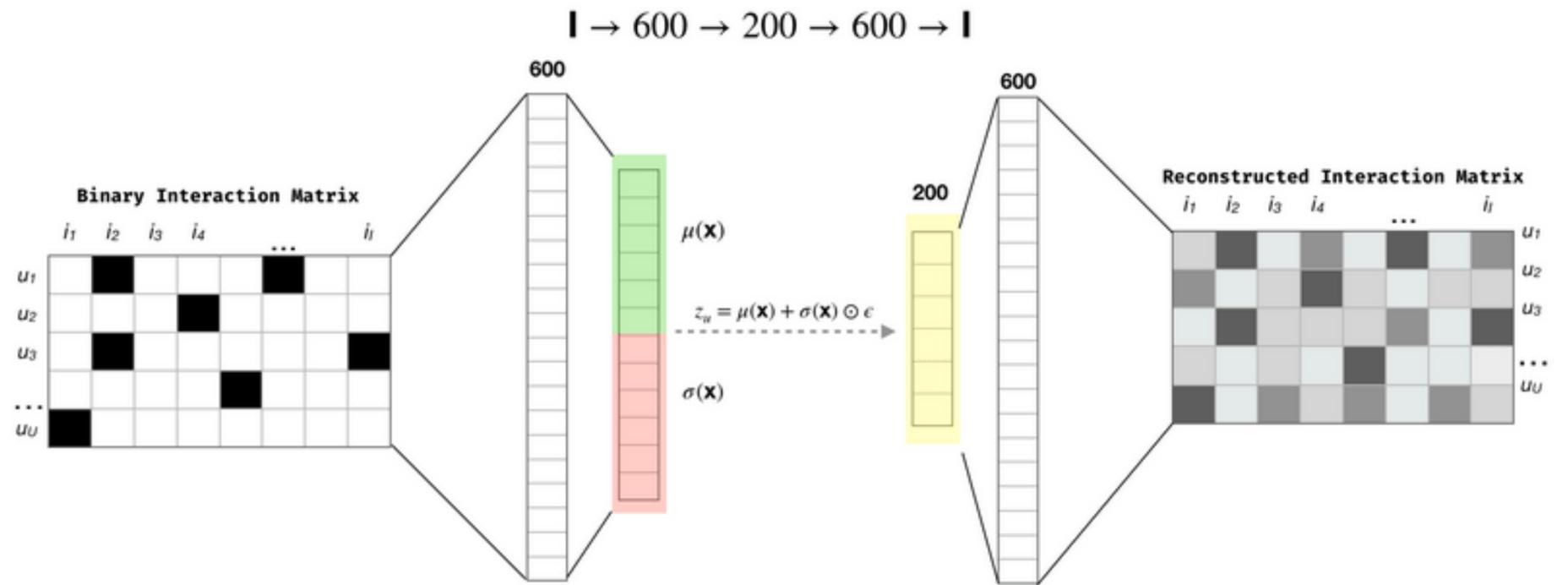
Autoencoder Experiments

BASELINE MODELS

Collaborative Denoising Autoencoder
(Wu et al., 2016)



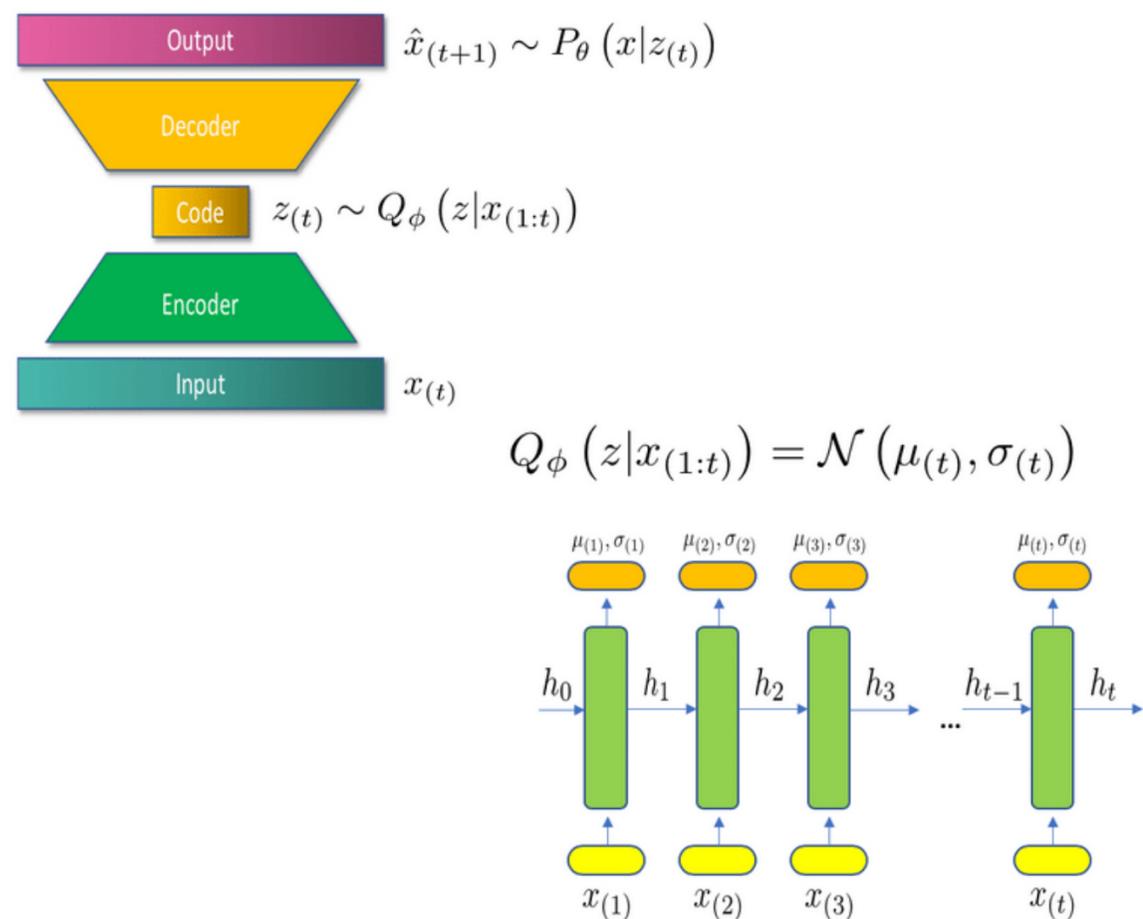
Multinomial Variational Autoencoder
(Liang et al., 2018)



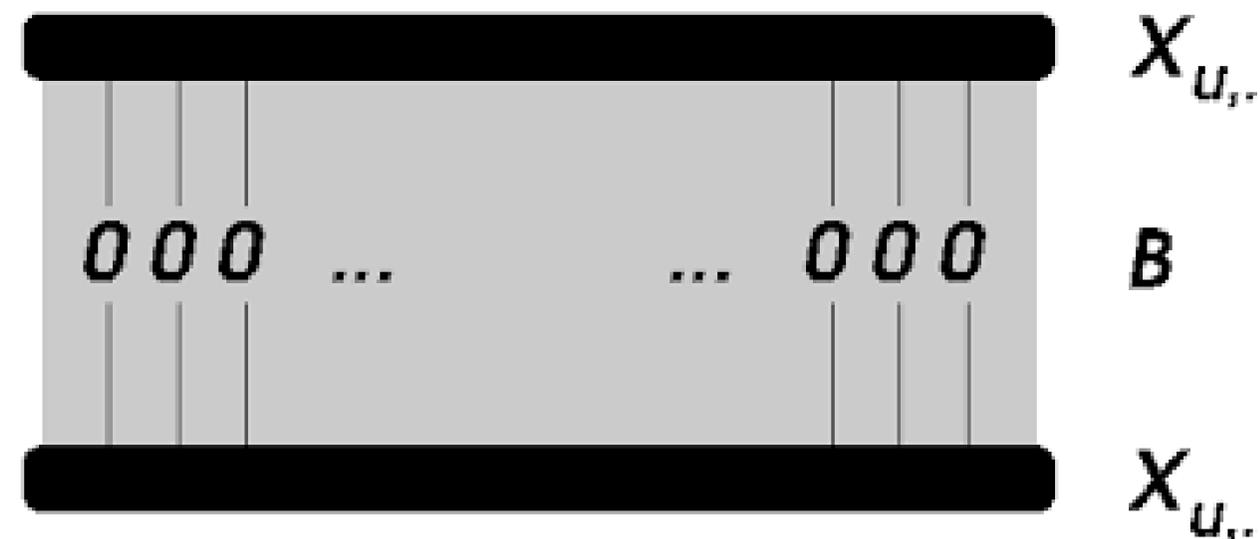
Autoencoder Experiments

BASELINE MODELS

Sequential Variational Autoencoder
(Sachdeva et al., 2019)



Embarrassingly Shallow Autoencoder
(Steck, 2019)



MetaRec-AE

BASE MODEL

Vanilla Autoencoder

$$\hat{r}_{ui} = (\text{recon}(r_{ui}, \hat{\theta}))$$

$$\text{recon}(r_{ui}; \theta) = f(W \cdot g(Vr_{ui} + \mu) + b)$$

LOSS FUNCTION

Binary Cross-Entropy Loss with L2 Regularization

$$L_u(\theta) = -\frac{1}{m} \sum_{u=1}^m \|(r_{ui} \log \hat{r}_{ui}) + (1 - r_{ui}) \log(1 - \hat{r}_{ui})\|_0^2 + \frac{\lambda}{2} \cdot (\|W\|_2^2 + \|V\|_2^2)$$

EVALUATION METRICS

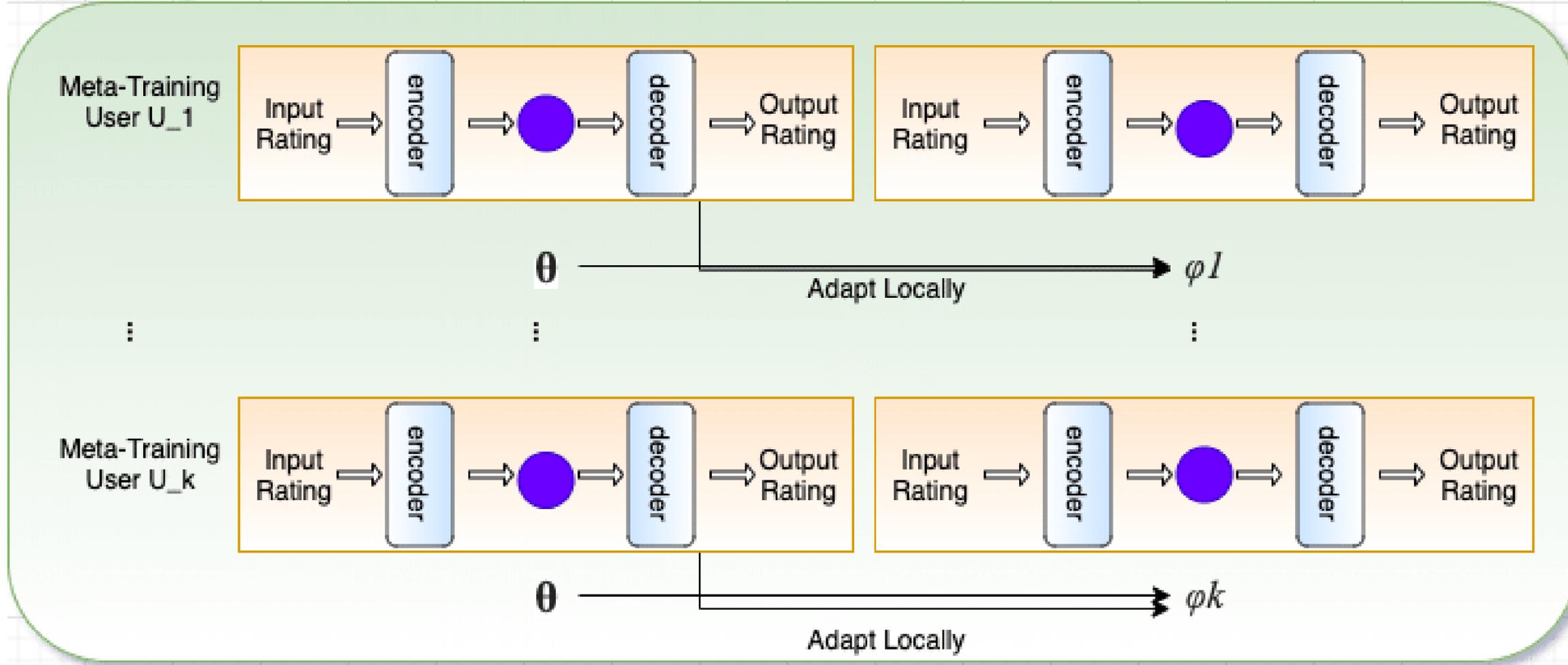
- Top-K Recommendation with Implicit Feedback
- Precision
- Recall
- Normalized Discounted Cumulative Gain

$$\text{Precision@}k = \frac{\text{Hits@}k}{k}$$

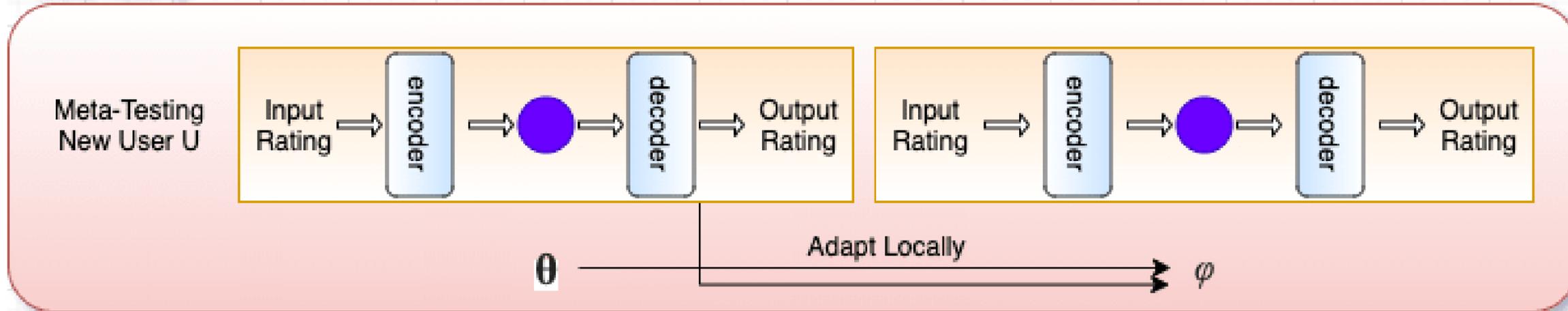
$$\text{Recall@}k = \frac{\text{Hits@}k}{|R|}$$

$$\text{NDCG@}k = \frac{\text{DCGs@}k}{\text{IDCG@}k}$$

Meta-Training



Meta-Testing



Ranking Results

Models	Precision@100	Recall@100	NDCG@100	Training Time
CDAE	8.94	41.37	25.28	17m29s
MultVAE	8.86	41.15	25.08	6m31s
SVAE	8.18	58.49	38.07	6h37m19s
ESAE	7.57	41.81	25.61	10m12s
MetaRec-AE (Ours)	8.34	55.12	33.06	18m24s

- Train-Valid-Test Split: 80-10-10
- Trained for 100 epochs with early stopping
- MetaRec-AE had an average performance across three metrics (Higher values are better)
- SVAE was the best performing model in Recall and NDCG metrics
- MultVAE took the shortest time to train
- ESAE performed reasonably well

Conclusion

PART 6



Problem Formulation

RECOMMENDATION TASK

- Applications
- Challenges
- Collaborative Filtering
- Linear Models
- Neural Network Models

Proposed Framework

METAREC

- Model-Agnostic-Meta-Learning
- Leverages Learning From Previous Users To New Users
- Accurate: High Evaluation Metrics
- Rapid: In Small Number of Steps
- Efficient: Using Few Examples

Experimental Results

VS STATE-OF-THE-ARTS

- Matrix Factorization Models
- Multi-Layer Perceptron Models
- Auto-Encoder Models
- Explicit and Implicit Feedback
- Improved Accuracy Performance
- Computational Cost Tradeoff



Areas of Improvement

NOTES FOR FUTURE RESEARCH

Make Changes To The Base Model $F(\Theta)$

- Complexify Them
- Simplify Them

Better MAML Training

- Training Instability
- Second-Order Derivative Cost
- Fixed Learning Rates During Updates

Areas of Improvement

NOTES FOR FUTURE RESEARCH

Other Meta-Learning Schemes For Recommendations

- Black-Box Meta-Learning
- Non-Parametric Meta-Learning

Addressing Scalability and Sparsity Challenges

- Shorter Training Time ~ Better Scalability
- Warm Users vs Cold Users Setup

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- Dawen Liang, Rahul Krishnan, Matthew Hofman, and Tony Jebara. **Variational Autoencoders For Collaborative Filtering**. 2018.
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Thank You!

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Codebase: github.com/khanhnamle1994/MetaRec

Appendix

Extra Details



MetaRec-MF

Algorithm 1: MAML Algorithm for MetaRec-MF

Input : Trainable global parameters θ , user set U , local and global hyper-parameters α, β

Output: Learned global parameters θ

```
1 Initialize  $\theta$  randomly;
2 while not converged do
3   | Sample a batch of users  $B$  from  $U$ ;
4   | for user  $u \in B$  do
5   |   | Evaluate the gradient  $\nabla_{\theta} L_u(F_{\theta})$ ;
6   |   | Perform the local update  $\phi_u \leftarrow \theta - \alpha \nabla_{\theta} L_u(F_{\theta})$ ;
7   | end
8   | Perform global update  $\theta \leftarrow \theta - \beta \sum_u L_u(F_{\phi_u})$ 
9 end
```

MetaRec-MLP

Algorithm 2: MAML Algorithm for MetaRec-MLP

Input : Trainable global parameters θ , user set U , local and global hyper-parameters α, β

Output: Learned global parameters θ

- 1 Initialize θ randomly;
- 2 Initialize ϕ randomly;
- 3 **while** *not converged* **do**
- 4 Sample a batch of users B from U ;
- 5 **for** *user* $u \in B$ **do**
- 6 Evaluate the gradient $\nabla_{\phi_u} L_u(F_{\theta, \phi_u})$;
- 7 Perform the local update $\phi_u \leftarrow \phi_u - \alpha \nabla_{\phi_u} L_u(F_{\theta, \phi_u})$;
- 8 **end**
- 9 Perform global update $\theta \leftarrow \theta - \beta \sum_u \nabla_{\theta} L_u(F_{\theta, \phi_u})$;
- 10 Perform global update $\phi \leftarrow \phi - \beta \sum_u \nabla_{\phi} L_u(F_{\theta, \phi_u})$
- 11 **end**

MetaRec-AE

Algorithm 4: MAML Algorithm for MetaRec-AE

Input : Trainable global parameters θ , user set U , local and global hyper-parameters α, β

Output: Learned global parameters θ

```
1 initialize  $\theta^{(0)}$ ;  
2  $i = 0$ ;  
3 while not converged do  
4   for  $u \in U$  do  
5     update autoencoder  
6     adapt locally:  $\phi^u = \theta^{(0,i)} - \alpha \nabla_{\theta} L(\theta^{(0,i)})$   
7   end  
8   update globally:  $\theta^{(0,i+1)} \leftarrow \theta^{(0,i)} - \beta \nabla_{\phi} L(\phi^u)$   
9    $i \leftarrow i + 1$   
10 end
```
